

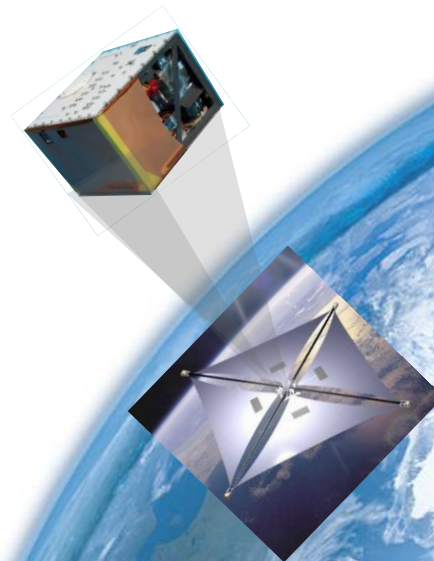


40<sup>th</sup> IEEE Aerospace Conference 2019

# Solar Sails for Planetary Defense & High-Energy Missions

**Jan Thimo Grundmann<sup>(1)\*</sup>, Waldemar Bauer<sup>(1)</sup>, Jens Biele<sup>(2)</sup>, Ralf Boden<sup>(3)</sup>, Kai Borchers<sup>(1)</sup>, Matteo Ceriotti<sup>(4)</sup>, Federico Cordero<sup>(5)</sup>, Bernd Dachwald<sup>(6)</sup>, Etienne Dumont<sup>(1)</sup>, Christian D. Grimm<sup>(1)</sup>, David Herčík<sup>(7)</sup>, Tra-Mi Ho<sup>(1)</sup>, Rico Jahnke<sup>(1)</sup>, Aaron D. Koch<sup>(1)</sup>, Alexander Koncz<sup>(8)</sup>, Christian Krause<sup>(2)</sup>, Caroline Lange<sup>(1)</sup>, Roy Lichtenheldt<sup>(9)</sup>, Volker Maiwald<sup>(1)</sup>, Colin McInnes<sup>(4)</sup>, Jan-Gerd Meß<sup>(1)</sup>, Tobias Mikschl<sup>(10)</sup>, Eugen Mikulz<sup>(1)</sup>, Sergio Montenegro<sup>(10)</sup>, Ivanka Pelivan<sup>(11)</sup>, Alessandro Peloni<sup>(4)</sup>, Dominik Quantius<sup>(1)</sup>, Siebo Reershemius<sup>(1)</sup>, Thomas Renger<sup>(1)</sup>, Johannes Riemann<sup>(3)</sup>, Michael Ruffer<sup>(10)</sup>, Kaname Sasaki<sup>(1)</sup>, Nicole Schmitz<sup>(8)</sup>, Wolfgang Seboldt<sup>(3)</sup>, Patric Seefeldt<sup>(1)</sup>, Peter Spietz<sup>(1)</sup>, Tom Sprowitz<sup>(1)</sup>, Maciej Sznajder<sup>(1)</sup>, Simon Tardivel<sup>(12)</sup>, Norbert Tóth<sup>(1)</sup>, Elisabet Wejmo<sup>(3)</sup>, Friederike Wolff<sup>(9)</sup>, Christian Ziach<sup>(3)</sup>**

*<sup>(1)</sup>DLR German Aerospace Center, Institute of Space Systems, Robert-Hooke-Strasse 7, 28359 Bremen, Germany – \*+49-(0)421-24420-1107, jan.grundmann@dlr.de – <sup>(2)</sup>DLR German Aerospace Center, Space Operations and Astronaut Training – MUSC, 51147 Köln, Germany – <sup>(3)</sup>Consultant to DLR Institute of Space Systems – <sup>(4)</sup>University of Glasgow, Glasgow, Scotland G12 8QQ, United Kingdom – <sup>(5)</sup>Telespazio-VEGA, Darmstadt, Germany – <sup>(6)</sup>Faculty of Aerospace Engineering, FH Aachen University of Applied Sciences, Hohenstaufenallee 6, 52064 Aachen, Germany – <sup>(7)</sup>Institute for Geophysics and Extraterrestrial Physics, Technical University Braunschweig, Germany – <sup>(8)</sup>DLR German Aerospace Center, Institute of Planetary Research, Rutherfordstr. 2, 12489 Berlin, Germany – <sup>(9)</sup>DLR German Aerospace Center, Robotics and Mechatronics Center, 82234 Wessling, Germany – <sup>(10)</sup>Informatik 8, Universität Würzburg, Am Hubland, 97074 Würzburg, Germany – <sup>(11)</sup>Fraunhofer Heinrich Hertz Institute Einsteinufer 37, 10587 Berlin, Germany – <sup>(12)</sup>CNES, Future Missions Flight Dynamics, 18 avenue E. Belin, 31401 Toulouse cedex 9, France*



Knowledge for Tomorrow

“When you’ve seen one asteroid,... ...or comet...  
 ...you’ve seen one asteroid. ...or comet.

until very recently, every asteroid visited looked different from all the others

- there are several approaches to classification but not all **connections** are understood:
  - spectral information → taxonomy ← ? → composition
  - shape & topography ← ? → interior structure → porosity ←
  - families ← orbital dynamics ← Yarkovsky → YORP ← ? ←
- ...however: each discipline sees a little light at the end of their tunnel
  - *taxonomy*: obvious patterns but composition inferred (cf. 2008 TC<sub>3</sub> / Almahata Sitta)
  - *shapes*: radar – the poor man’s flyby – shows >1 “top-like”, “cigar”, “bi-lobe”...
  - *orbits*: long-term monitoring makes small Yarkovsky & YORP effects quantifiable
- ...corollary: all these dots & models still need to be connected

➔ need to study many more asteroids – close-up, soon, affordable

1 km  
 ≈  
 ½ km

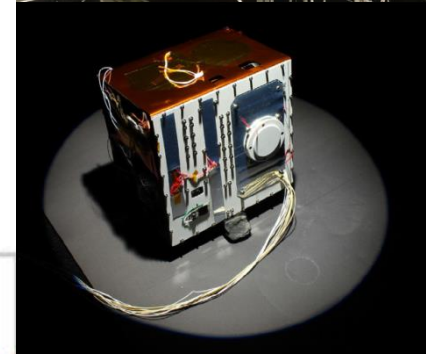
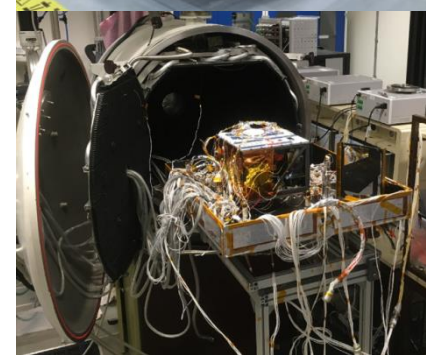


# getting a handle on asteroids: from target selection\* to ground truth

- all current & almost all future small solar system bodies science missions require sample in-situ analysis and/or return
- science can choose to interact with an asteroid
  - planetary defence must
- all deflection methods interact with the target asteroid:
  - gravity tractor – ion engine plume impinges on asteroid
  - kinetic impactor – transfers impulse & energy ( $\beta$ -factor)
  - laser ablation – evaporates surface, releases volatiles
  - solar concentrator – evaporates surface, releases volatiles
  - thruster attachment – soft landing of a fuel-laden spacecraft
  - albedo modification – covers or rearranges the surface layers
  - ...

→ *characterization by rendezvous with target or closely analog asteroid*  
 → *get to know **multiple Near-Earth Asteroids** before “the one”!*



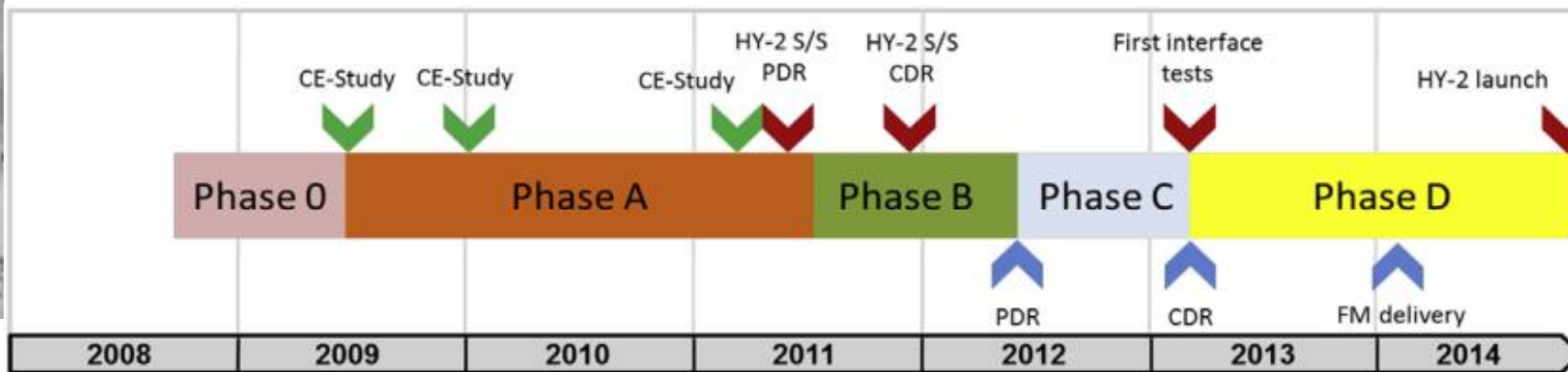


2018

## a brief history of...

## re-discovering responsive space

- when (...not if...) an impactor is found, the combination of...
  - extreme inaccessibility of almost all asteroid orbits
  - lead time from a *positive* prediction of impact to the expected impact
 ...will put extreme time pressure on the space segment
- very few launch windows & extreme  $\Delta v$  to rendezvous *or* very fast fly-by
- 60 years ago, real spaceflight was *invented* within  $\approx 2$  years from the word 'go'
- recent science missions take  $\approx 20$  years to design & build (e.g. Rosetta, Cassini)
- MASCOT went forward to the past: 2 years from **PDR** to **FM delivery**



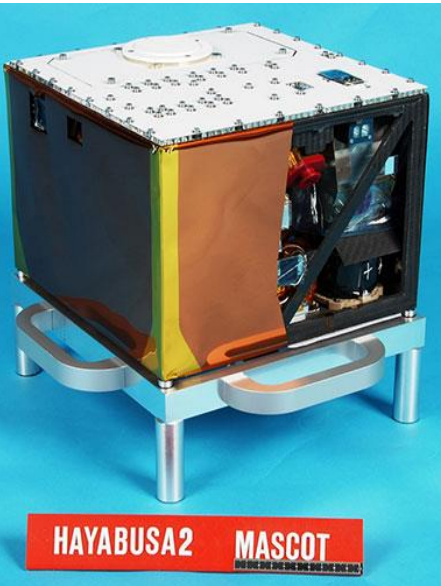
figures: Grimm et al, 2018  
USAF via The Space Review



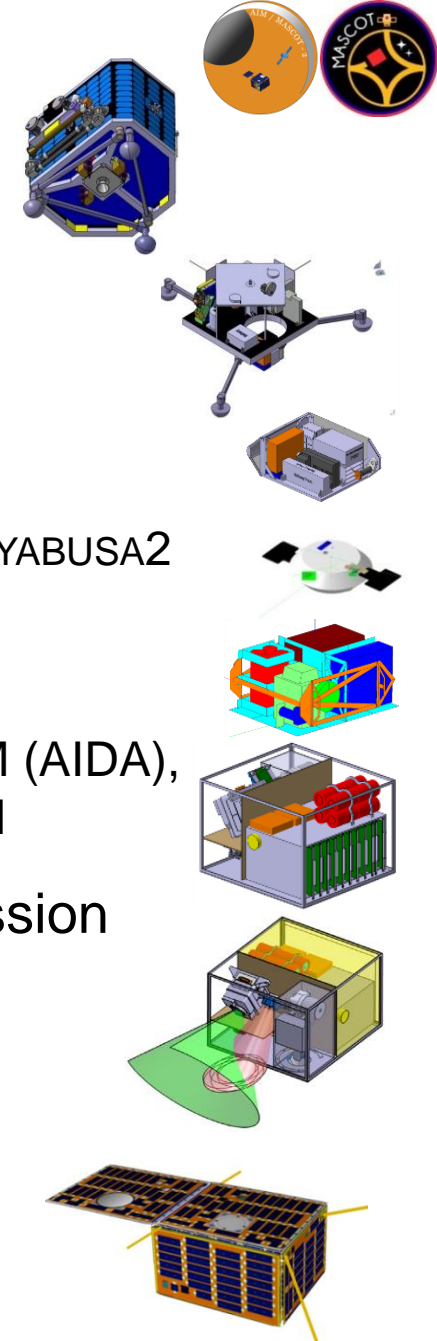
1959



# 'now-term' technology: a Lander as an Instrument – MASCOT

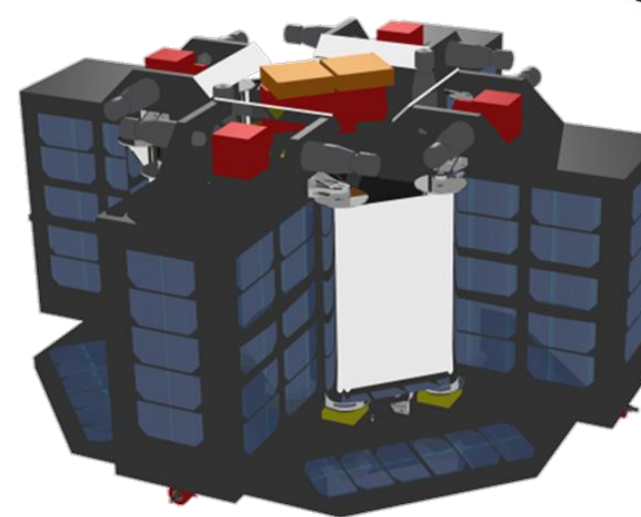
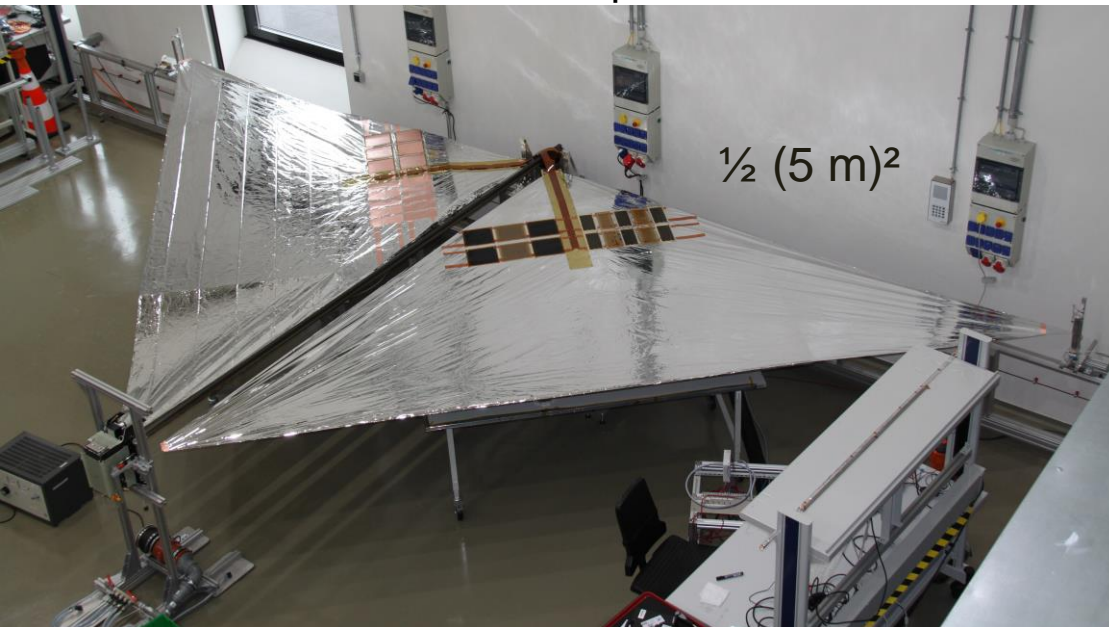


- MASCOT – **M**obile **A**steroid **S**urface **S**cout
  - 2008-2011: concept & CE studies
  - 2012-2014: from paper design to FM delivery
  - 2014-2018: cruise to km-sized PHA (162173) Ryugu aboard JAXA's HAYABUSA2
- landed on October 3<sup>rd</sup>, 2018 for its 17 hours scouting mission (*during IAC 2018*)
- with precursor and follow-on studies, e.g. MARCOPOLO or MASCOT2 for AIM (AIDA), a ready-to-go repertoire for many missions has already been created
- lander at the instrument level of a mainstream mission
- serves 4 full planetary science quality instruments
- high degree of design re-use
- constraints-driven design
- high-density design
- nanospacecraft

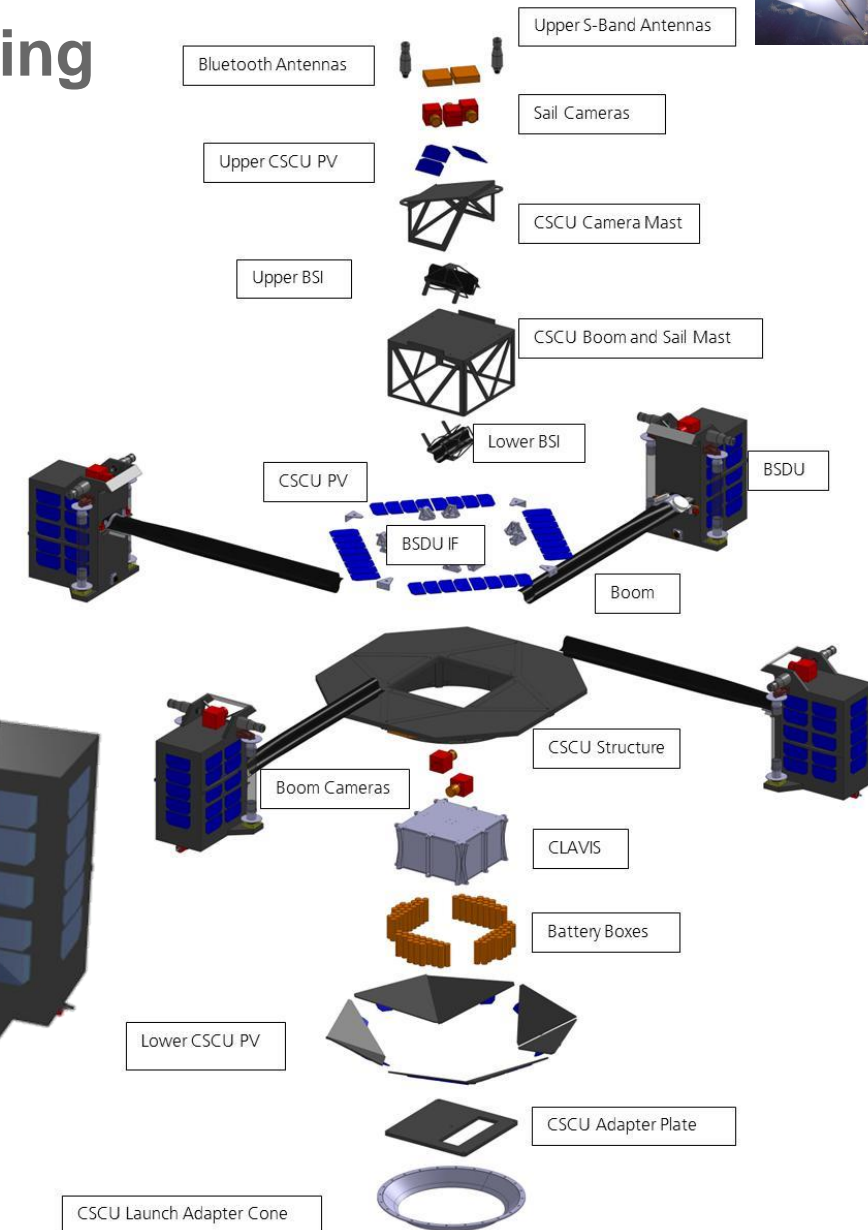


# near-term technology: Solar sail with carefree handling – GOSSAMER-1 EQM

- the 3-step DLR-ESTEC GOSSAMER Roadmap to Solar Sailing was set up in 2009 to develop key technologies for science missions
- 1<sup>st</sup> step: GOSSAMER-1 EQM was built & qualification tested
- development was stopped after reaching TRL 5
- a PFM design was ready to proceed
- a launch opportunity was available
- all-launchers load envelope



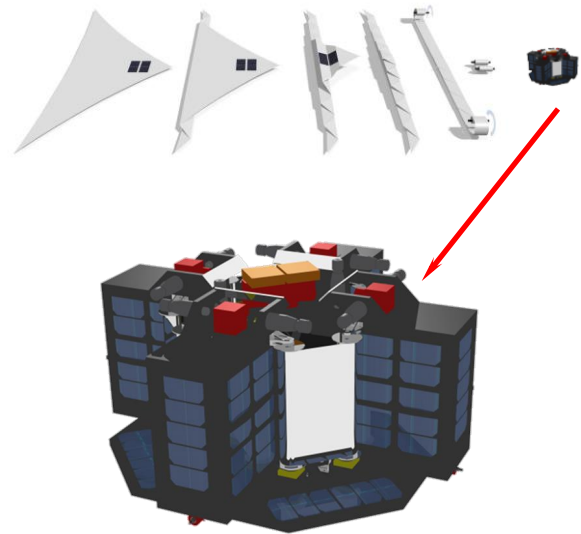
$\approx 30 \dots \leq 37.6 \text{ kg}, 79 \cdot 79 \cdot 50 \text{ cm}^3$



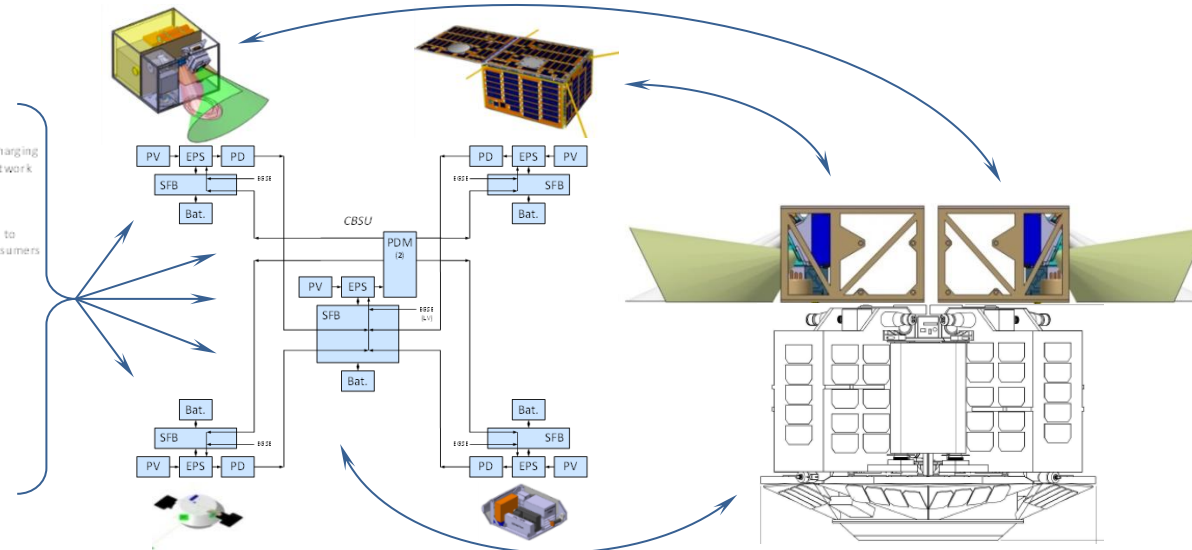
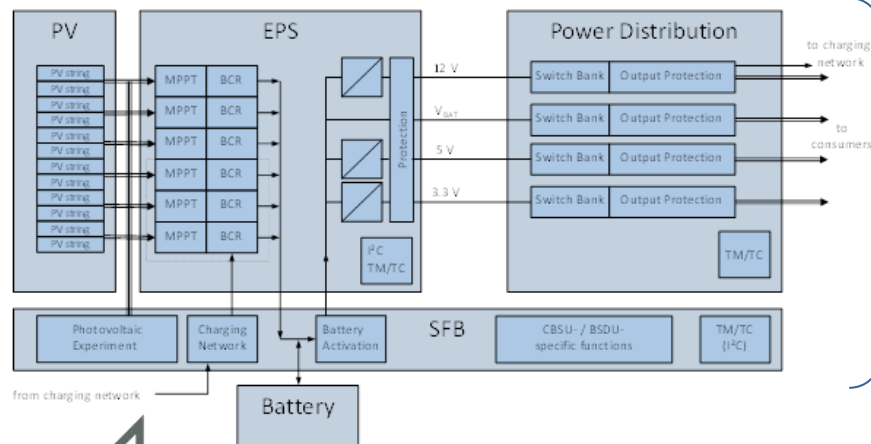
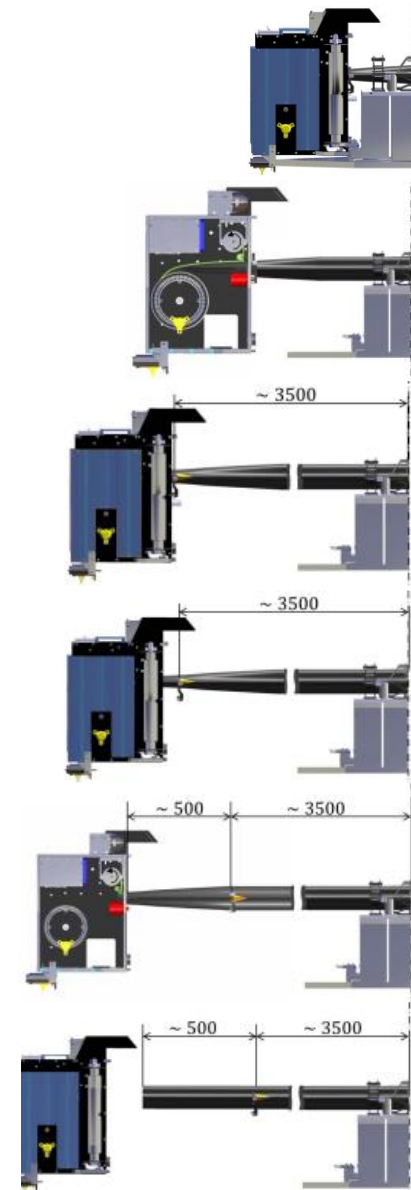




## integrating all that: ...and landers

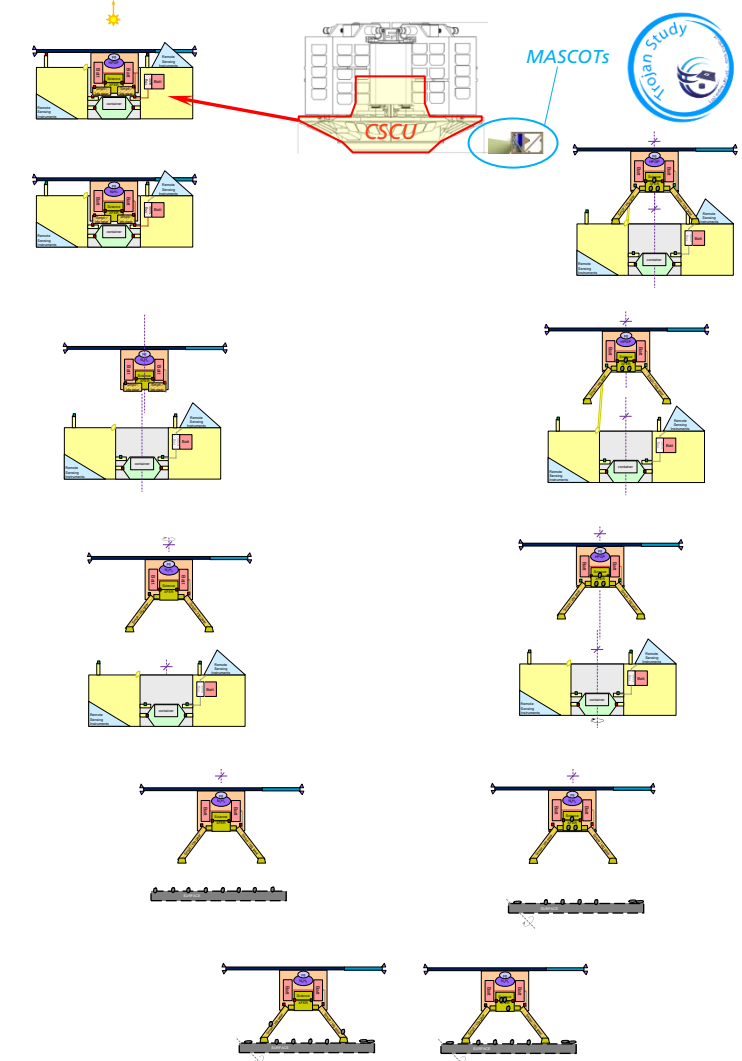
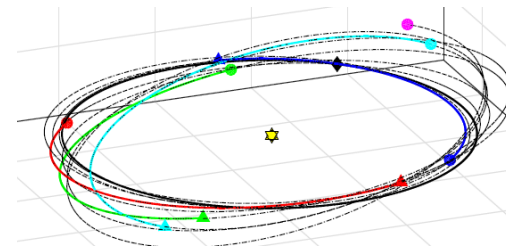
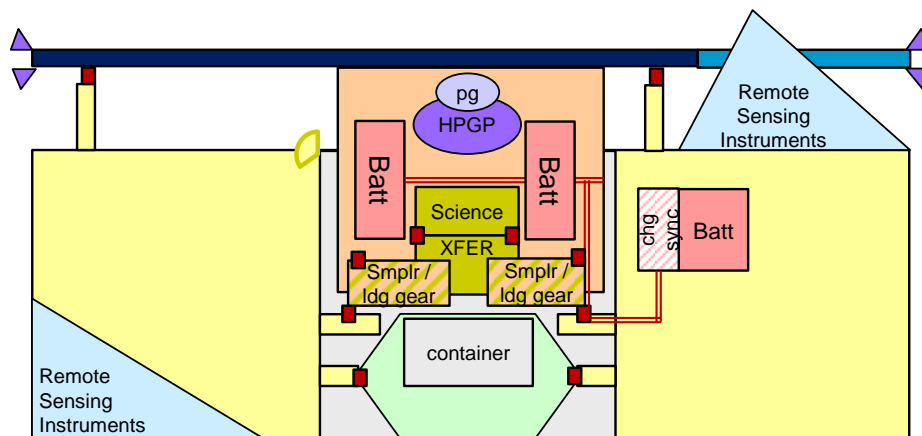


- 1 GOSSAMER sail at launch = 5 independent spacecraft connected to act as one
- electrical – thermal – mechanical face-to-face interfaces enable energy transfer
- additional plane of interfaces for 'payload' side on Central Sailcraft Unit (CSCU)
- interfaces between the CSCU and the 4 Boom Sail Deployment Units (BSDU) already use elements also present in MASCOT, e.g. Umbilical Connectors
- MASCOT already has suitable interfaces to its carrying structure (MESS)
- mutual support of landers and sailcraft extends concept into cruise



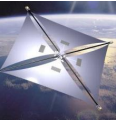
## ...and returning them to the Earth

- sample return requires propulsion
  - pre-deployment propulsion capability can be useful for large sails
  - propulsion entirely on lander, control divided
- propulsion power drives lander battery & photovoltaics
  - the core sailcraft needs pre-deployment photovoltaics (PV)
- battery shared, mostly on lander
- rigid PV completely on lander
- flexible cruise PV on sail



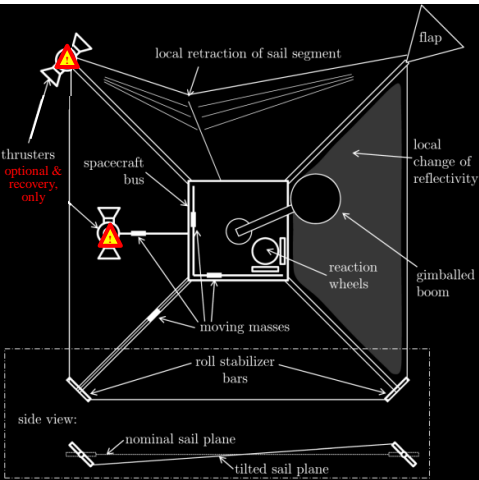
Object	Stay time [days]	Start	End	Time of flight [days]
Earth	//	10 May 2025	26 Feb 2027	657
2000 SG <sub>344</sub>	123	29 Jun 2027	06 Sep 2028	436
2015 JD <sub>3</sub>	164	18 Feb 2029	24 Sep 2030	584
2012 KB <sub>4</sub>	160	04 Mar 2031	29 Sep 2032	576
2008 EV <sub>5</sub>	160	18 Mar 2033	22 May 2036	1161
Earth	∞			





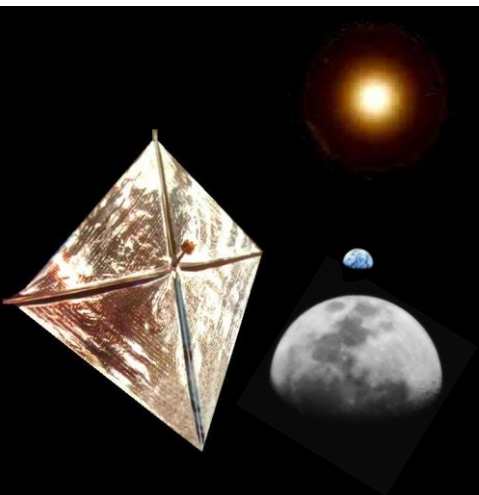
# Performance of GOSSAMER technology

benchmark: Multiple NEA Rendezvous trajectories @  $a_c = 0.2 \text{ mm/s}^2$



## GOSSAMER-2 – high-orbit attitude & thrust vector control

- $(20...25 \text{ m})^2$  sail area
- orbit where solar radiation pressure is dominant
- implementation of several to “all” control methods
- *thrusters only for recovery*



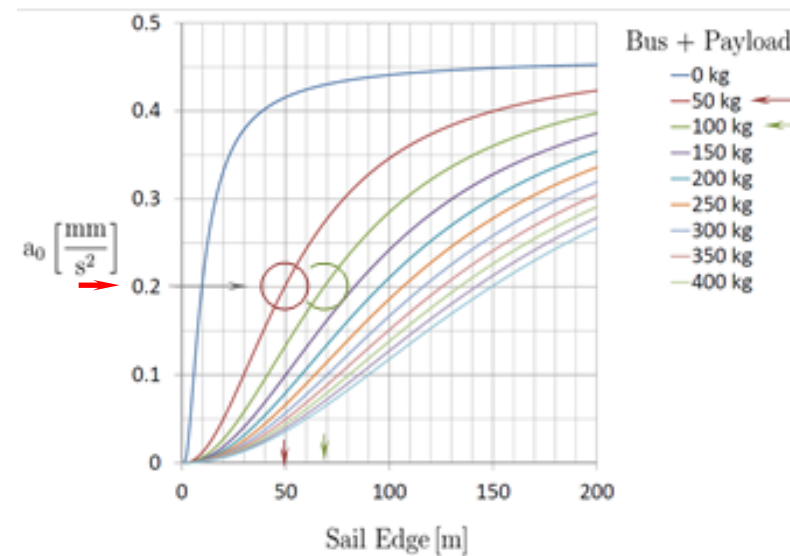
## GOSSAMER-3 – all-up proof test

- $(50 \text{ m})^2$  sail area
- initial orbit high enough to spiral out (sail up)
- **prove that sails can operate science missions**

### GOSSAMER-1 technology:

- $0.2 \text{ mm/s}^2$  & **50 kg** bus & payload →  $(50 \text{ m})^2$  membrane
- $0.2 \text{ mm/s}^2$  & **100 kg** bus & payload →  $(70 \text{ m})^2$  membrane
- $0.2 \text{ mm/s}^2$  & **150 kg** bus & payload →  $(85 \text{ m})^2$  membrane

➔ ESPA / ASAP compatible micro-spacecraft



Bus (Gos-1 + X-Band)		≈ 30 kg
Mother Spacecraft Science Instruments		≈ 10 kg

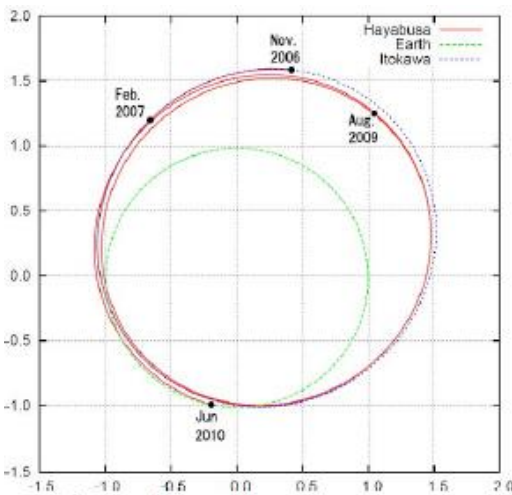
Lander		
PHILAE		98 kg
SPS Lander		100 kg
1 MASCOT		10 kg
5 MASCOTS		50 kg

+10 kg  
support  
structure

## state of the art:

## DAWN – 2-asteroid rendezvous

## HAYABUSA &amp; HAYABUSA2 – 1-asteroid sample-return



- HAYABUSA2 is currently at (162173) Ryugu
  - $\Delta v$  capability  $\approx 3.2$  km/s from 66 kg Xe propellant
  - up to  $\approx 3.5$  km/s if filled up to 73 kg Xe capacity
- HAYABUSA returned samples from (25143) Itokawa
  - $\Delta v$  capability  $\approx 4.0$  km/s from 66 kg Xe propellant
- DAWN orbited (4) Vesta & orbits (1) Ceres
  - $\Delta v$  capability  $\approx 13$  km/s from 275 kg Xe propellant

common feature:

high-performance electric propulsion

...and the limit?

- SESAME (Maiwald & Marchand, 2016)
  - science payload 33 kg (orbiter) + 5\* 4.3 kg (landers)
  - trajectory to **5 NEAs** of  $\approx 200$  candidates
  - **primarily astrodynamic target selection**
  - targets tied to launch date

Property	Value
Departure Date from Earth	21 March 2023 ←
Arrival @ 5 <sup>th</sup> target	26 February 2030
Total $\Delta v$	→ 16.6 km/s
Wet mass	1,571 kg
Xenon fuel mass	451 kg
Bi-propellant mass	125 kg

Table 7: Mission parameters of SESAME

Target Body Data	Absolute Magnitude (H)	Orbit Condition Code (OCC)	Observation opportunities prior launch
2001QJ <sub>142</sub>	23.4	6	2012
2000SG <sub>344</sub>	24.8	2	none
2009OS <sub>5</sub>	23.6	5	2014-2020
2007YF	24.8	5	2021
1999AO <sub>10</sub>	23.9	6	2018, 2026

Table 8: Mission target data

Body	Arrival Date	Departure Date
Earth	-	21 Mar 2023
2001QJ <sub>142</sub>	31 Jan 2024	22 Jul 2024
2000SG <sub>344</sub>	9 Oct 2025	8 Mar 2026
2009OS <sub>5</sub>	27 Mar 2027	28 Sep 2027
2007YF	16 Dec 2028	19 May 2029
1999AO <sub>10</sub>	26 Feb 2030	4 Sep 2030

Table 9: Trajectory data.





## ...and now without fuel tank: Multiple NEA Rendezvous by Solar Sail

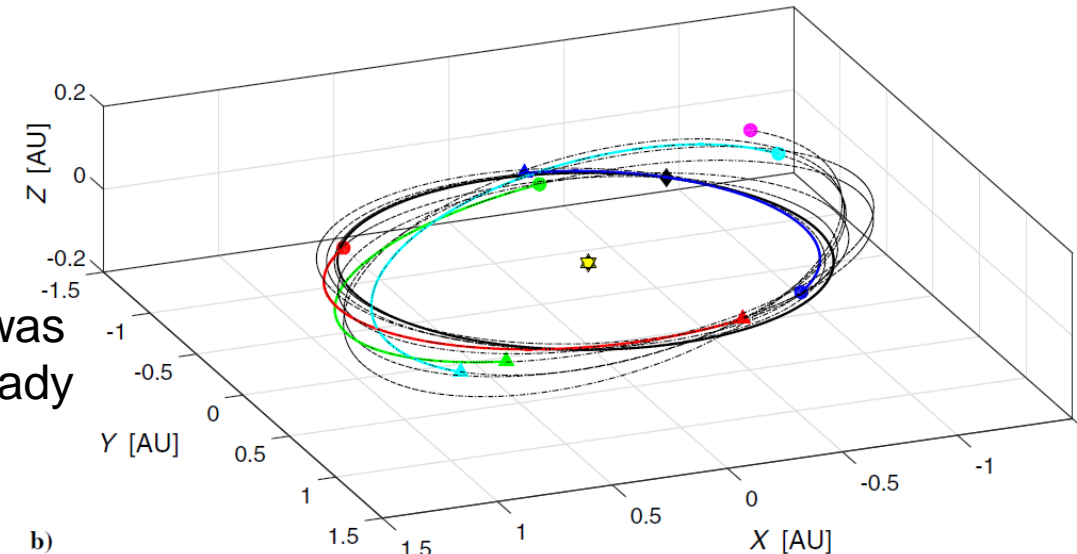
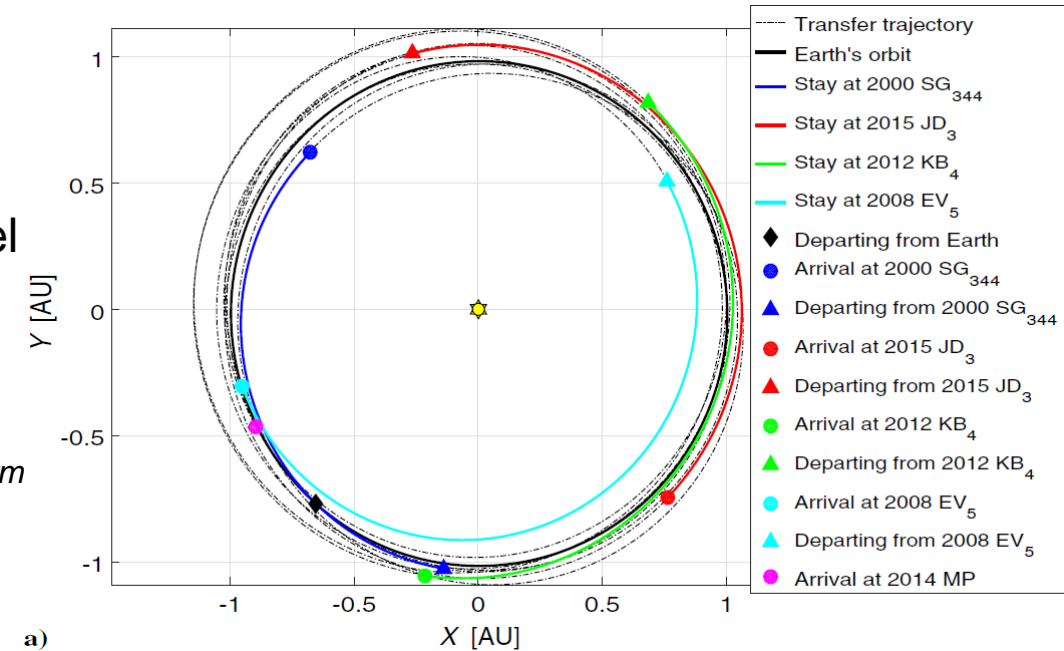
- solar sailing provides propulsion not limited by an amount of fuel

– *then what's the next limit?* –

how well it is designed, built, tested, flown & fixed

*mechanisms have been fixed in space without astronauts around: e.g. Voyager 1 scan platform*

- recent studies (Pelsoni et al., 2016-2018) demonstrate
  - 5 NEA stays for  $\geq 100$  days, each, in 10 years
  - accumulated  $\Delta v > 50 \text{ km/s}$  @  $a_c = 0.2 \text{ mm/s}^2$ 
    - asteroid-oriented target selection is feasible
    - at-launch & in-flight target change capability
- target-flexible Multiple NEA Rendezvous for planetary science was identified as a mission type uniquely feasible with solar sail already by the GOSSAMER Roadmap Science Working Groups





# 5 NEAs in 10 years

– many times a day

even restricted to PHA & NHATS targets, only,...

- there are 100's of possible NEA sequences for each launch date
- targets can be changed any time while in cruise or rendezvous
- now available sail technology is sufficient

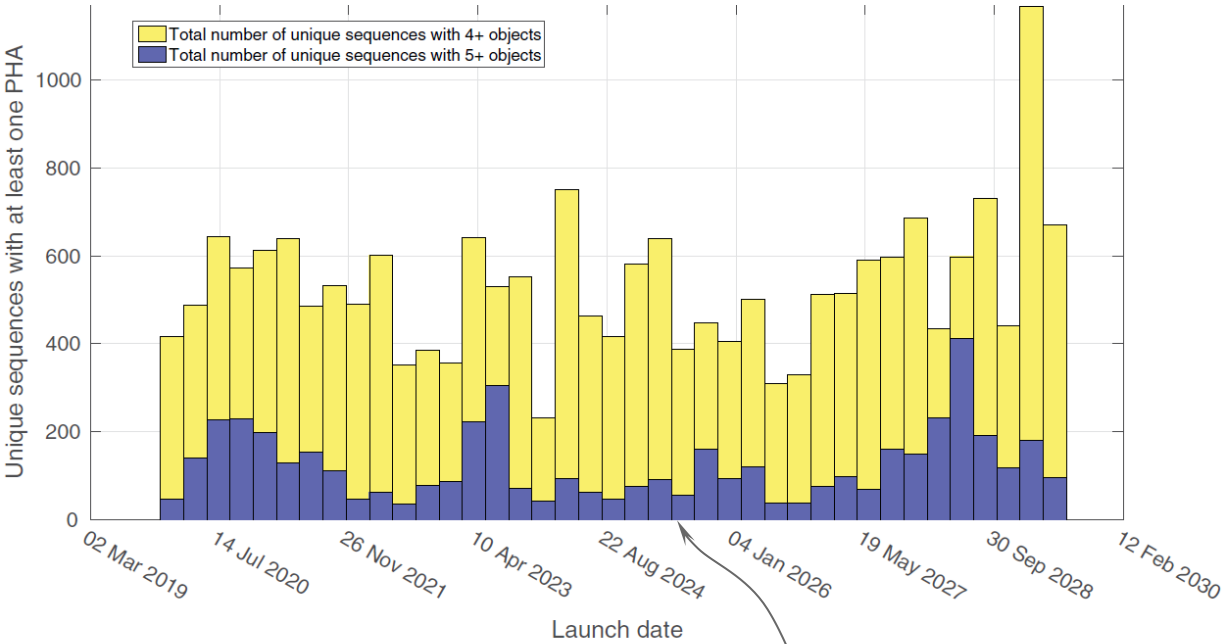


Fig. 7 Number of unique sequences with at least one PHA and four encounters as a function of the launch date.

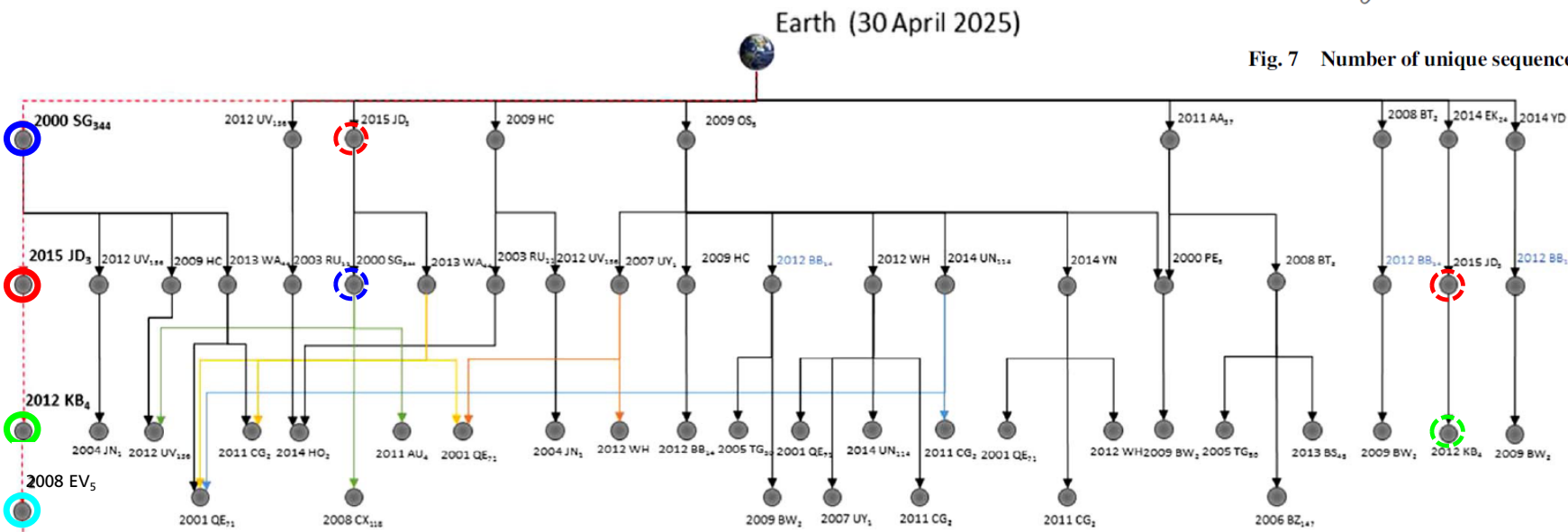


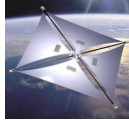
Fig. 8 Tree graph of first three legs of all sequences with five encounters found for launch date  $t_0 = 30$  April 2025.

Object	Stay time [days]	Start	End	Time of flight [days]
Earth	//	10 May 2025	26 Feb 2027	657
2000 SG <sub>344</sub>	123	29 Jun 2027	06 Sep 2028	436
2015 JD <sub>3</sub>	164	18 Feb 2029	24 Sep 2030	584
2012 KB <sub>4</sub>	160	04 Mar 2031	29 Sep 2032	576
2008 EV <sub>5</sub>	171	20 Mar 2033	30 Sep 2034	560
2014 MP	//			



figures: Peloni, Ceriotti, Dachwald, 2016



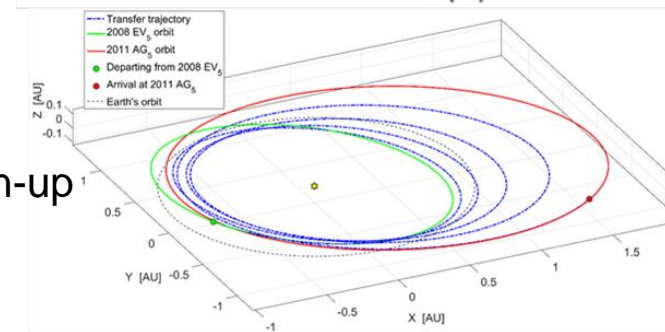
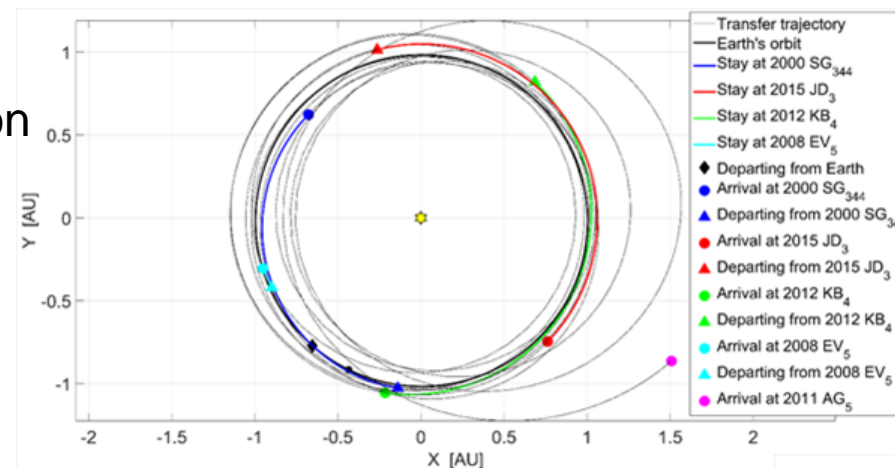


...and then still (have to) change your mind,...

– going after (fictitious) impactors by sail

- 2011 AG<sub>5</sub> – the PDC 2013 **Exercise** impactor, hits February 3<sup>rd</sup>, 2040
- fully optimized MNR mission launched in 2025 can be diverted to rendezvous 2011 AG<sub>5</sub> in time

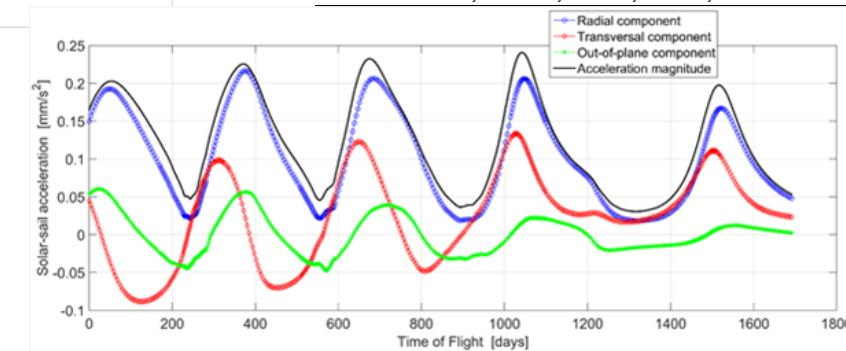
- optimized trajectory change:
- diverting from an ongoing MNR mission
- rendezvous feasible at  $a_c = 0.2 \text{ mm/s}^2$



Object	Stay time [days]	Start	End	Time of flight [days]
Earth	//			
2000 SG <sub>344</sub>	123	10 May 2025	26 Feb 2027	657
2015 JD <sub>3</sub>	164	29 Jun 2027	06 Sep 2028	436
2012 KB <sub>4</sub>	160	18 Feb 2029	24 Sep 2030	584
2008 EV <sub>5</sub>	7.5	04 Mar 2031	29 Sep 2032	576
2011 AG <sub>5</sub>	987 to ⊕	07 Oct 2032	25 May 2037	1691

Object	2000 SG <sub>344</sub>	2015 JD <sub>3</sub>	2012 KB <sub>4</sub>	2008 EV <sub>5</sub>	2011 AG <sub>5</sub>
Orbital type	Aten	Amor	Amor	Aten	Apollo
Semi-major axis [AU]	0.977	1.058	1.093	0.958	1.431
Eccentricity	0.067	0.009	0.061	0.083	0.390
Inclination [deg]	0.111	2.730	6.328	7.437	3.681
Absolute magnitude [mag]	24.7	25.6	25.3	20	21.8
Estimated size [m]	35 – 75	20 – 50	20 – 50	260 – 590	110 – 240
EMOID [AU]	0.0008	0.054	0.073	0.014	0.0002
PHA	no	no	no	yes	yes
NHATS	yes	yes	yes	yes	no

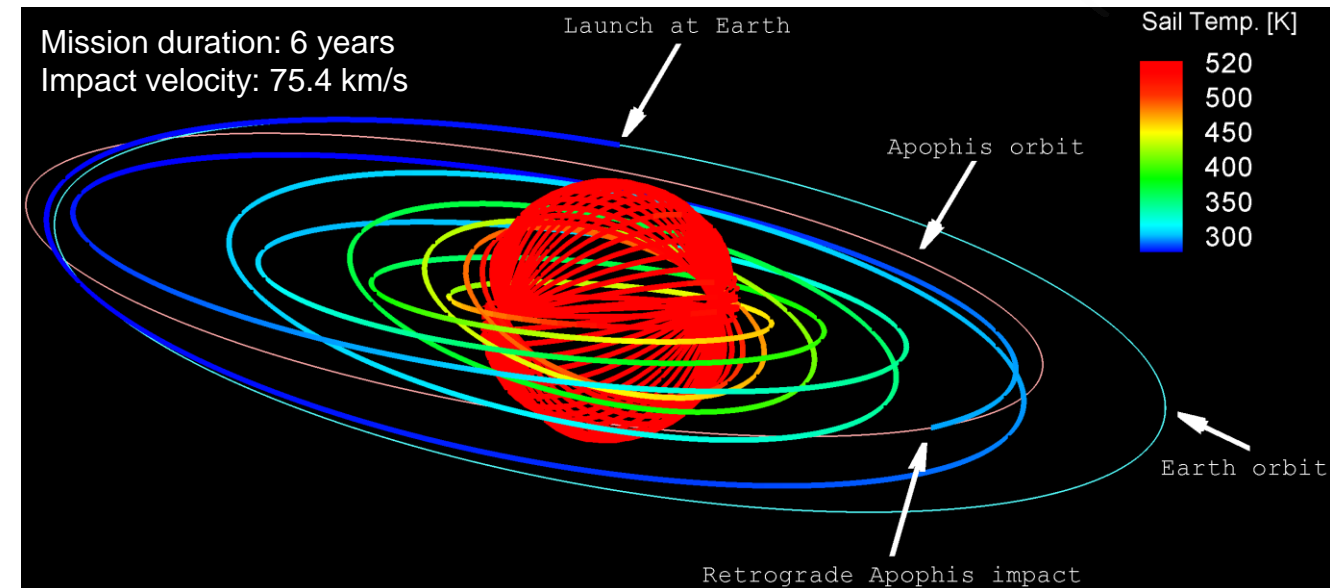
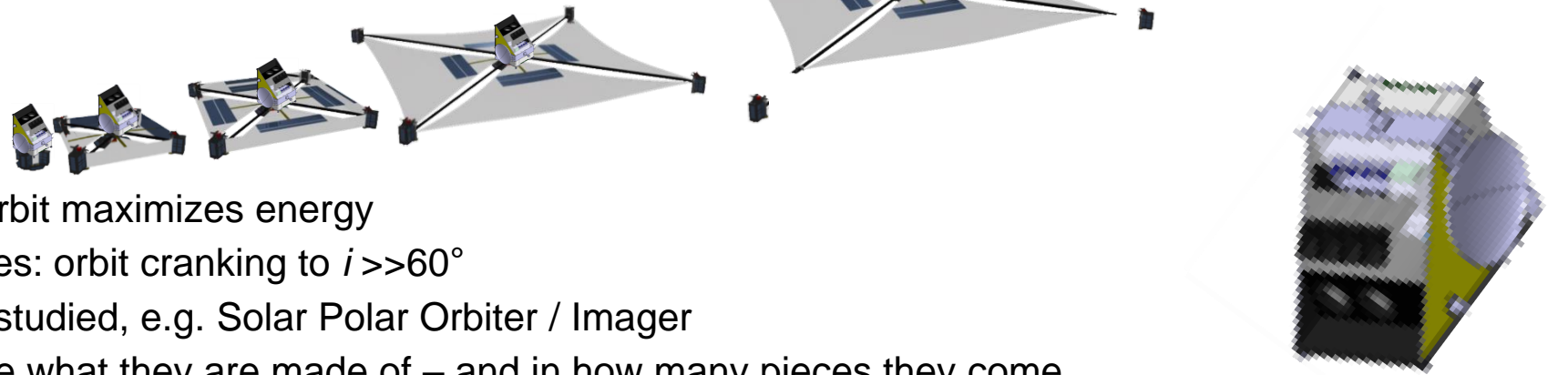
- PDC 2017 target:
  - hits in 2027
  - too soon for this 2025 launch study
  - 2020 launch can reach it only in 2030
  - useful mission: tracking, keyhole clean-up



## ...and finally, fix it. going for “*the one*” head-on by sail

What the cameras  
aboard Ranger 6  
will shoot

- kinetic energy  $\sim v^2$  – retrograde orbit maximizes energy
- one of solar sails' unique capabilities: orbit cranking to  $i \gg 60^\circ$
- payload-drop missions have been studied, e.g. Solar Polar Orbiter / Imager
- Kinetic Energy Impactors don't care what they are made of – and in how many pieces they come
- multiple small spacecraft: add robustness
- retrograde matched orbit: re-try capability
- need to develop sails to  $a_c \approx 0.5 \text{ mm/s}^2$



figures NASA; Dachwald,  
Kahle, Wie, 2006/2007





## Conclusions

- currently available qualified solar sail and recently flown lander technology enables
  - small spacecraft approach to asteroid related science and applications missions
  - large-scale exploration of the entire Near Earth Asteroid population
  - mass-to-orbit efficient mitigation
- complete solar sail technology development is required to realize these missions
- the experience of MASCOT refreshes the original responsive approach to space
- small-spacecraft technology leads towards an affordable development through re-use





**thank you for your attention!**

**– don't hesitate to send in questions ☺**

